

CSc 134

Database Management Systems

9. Indexing Structures for Files

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Single-level ordered indexes

◆ Structure

- Ordered index file
 - ◆ Small, easy to do binary search
- A list of pointers to disk blocks

◆ Dense index vs. sparse (nondense) index

- Dense: One index entry for every record of data files.
- Sparse: Has index entries for only some of the search values.

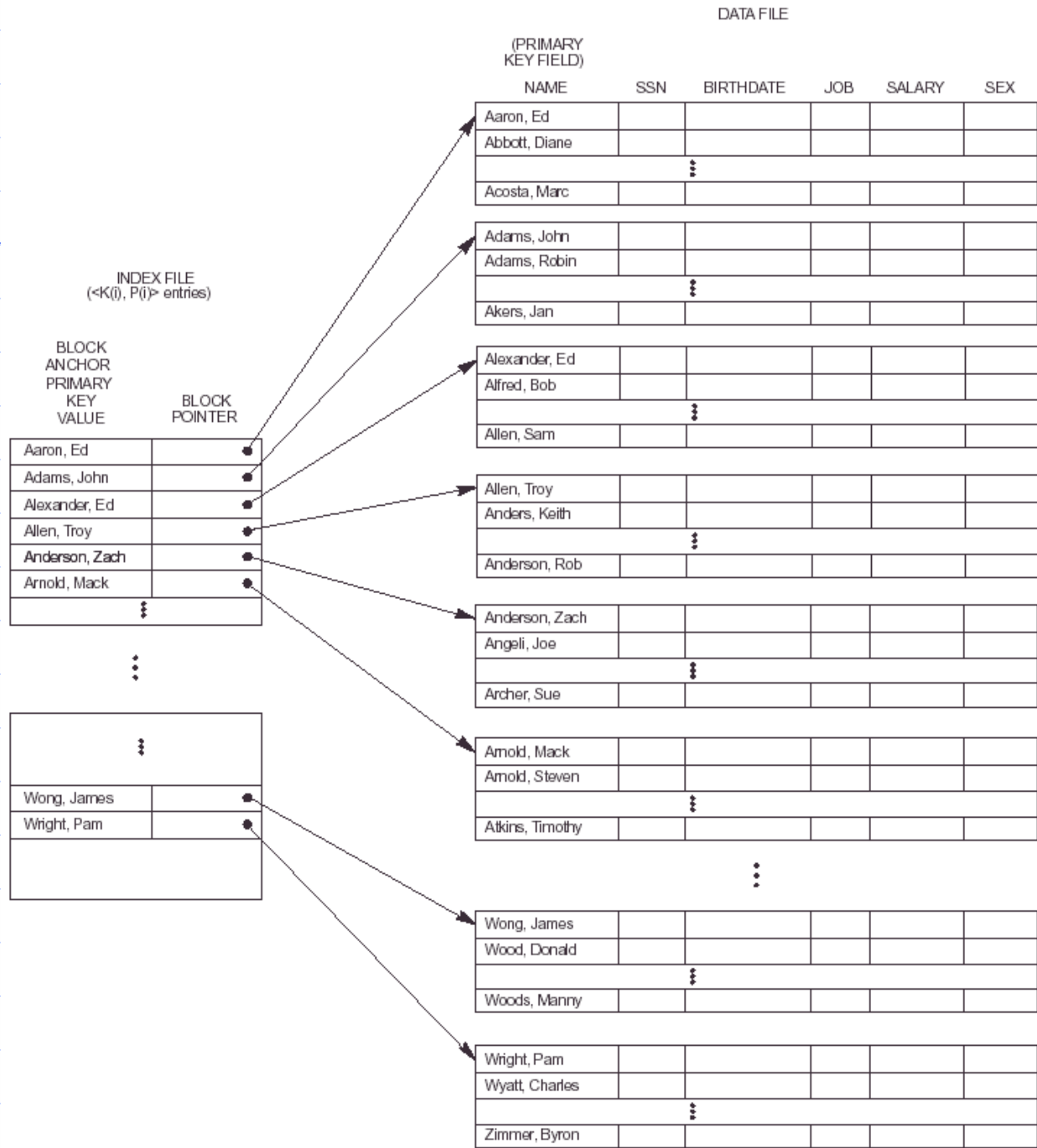
◆ Primary index

◆ Clustering index

◆ Secondary index

Primary Indexes

- ◆ Specified on the *ordering key field* of an ordered file of records.
- ◆ Ordering key field is used to **physically** order the file records on disk.
- ◆ Index file consists of index entry (or index record)
- ◆ index entry: $\langle \text{primary key, pointer to disk block} \rangle$
- ◆ index entry i : $\langle K(i), P(i) \rangle$
- ◆ 1 index entry --- 1 block in the data file
- ◆ Anchor record of the block (block anchor): first record in each block of the data file.
- ◆ Dense index or sparse index 😊?



Access a record

- ◆ Load blocks of index files
- ◆ Search in index files
- ◆ load corresponding data file

Average time to access a record

- ◆ B: block size, R: record size, r: total number of records.
- ◆ blocking factor $bfr = \lfloor B/R \rfloor$ records per block
- ◆ A file has b block: $b = r/bfr$
- ◆ A file with **b** block, binary search to find a specific record needs to access $\log_2 b$ block
 - Linear search $b/2$.
- ◆ Example 1
 - $r=30,000, B=1024, R=100$.
 - How many block accesses are needed for a binary search on the data file?

Example 1 (Cont.)

- ◆ Use primary index
 - ordering key field: $V=9$ bytes, a block pointer $P=6$ bytes.

Clustering Indexes

- ◆ Files are physically ordered on non-key field - clustering field
- ◆ Clustering field does not required to have distinct value.
- ◆ Clustering index
- ◆ <index field, pointer>
 - 1 entry for each **distinct value** of the clustering field.
 - a pointer to the **first block** in the data file that has a record with that value for its clustering field.
- ◆ Figure

Insertion

- ◆ Make insertion more efficient:
It is common to reserve a whole block (or a cluster of contiguous blocks) for each value of the clustering field.
- ◆ Figure

Secondary Indexes

- ◆ Provide a secondary means of accessing a file for which some primary access already exists
- ◆ Index entry
 - index field: nonordering field of the data file
 - pointer: either a block pointer or a record pointer

Secondary indexes

- ◆ Secondary key: Index field has a distinct value for every record
- ◆ One index entry for each record in the data file
- ◆ e.g. Block pointer (figure)
 - Load and search index block
 - Load appropriate block
 - A search for the desired record within the block
- ◆ Dense index

DATA FILE

INDEXING
FIELD
(SECONDARY
KEY FIELD)

INDEX FILE
($\langle K(i), P(i) \rangle$ entries)

INDEX FIELD VALUE	BLOCK POINTER
1	•
2	•
3	•
4	•
5	•
6	•
7	•
8	•
9	•
10	•
11	•
12	•
13	•
14	•
15	•
16	•
17	•
18	•
19	•
20	•
21	•
22	•
23	•
24	•

9			
5			
13			
8			
6			
15			
3			
17			
21			
11			
16			
2			
24			
10			
20			
1			
4			
23			
18			
14			
12			
7			
19			
22			

Example 2

◆ $r = 30,000, R=100, B=1024, b=3000$

◆ Linear search

- Require $b/2=3000/2 = 1500$ block accesses on the average

◆ Secondary index on non-ordering key field

$v=9, P=6$

Secondary index on a non-key field

- ◆ Numerous records in the data file can have the same value for the indexing field
- ◆ Options for implementation
 1. Several index entries with the same $K(i)$ value – one for each record.
 2. Variable-length records for the index entries
 $\langle K(i), \langle P(i,1), \dots, P(i,k) \rangle \rangle$
 3. $\langle K(i), P(i) \rangle$ points to a block of record pointers (figure)
If some $K(i)$ occurs in **too many** records (pointers cannot fit in one block), **a cluster or linked list of blocks** is used. Figure

Option 3

DATA FILE

(INDEXING
FIELD)

DEPTNUMBER NAME SSN JOB BIRTHDATE SALARY

BLOCKS OF
RECORD
POINTERS

INDEX FILE
(<K(i), P(i)> entries)

FIELD VALUE	BLOCK POINTER
1	•
2	•
3	•
4	•
5	•
6	•
8	•



3					
5					
1					
6					
2					
3					
4					
8					
6					
8					
4					
1					
6					
5					
2					
5					
5					
1					
6					
3					
6					
3					
8					
3					

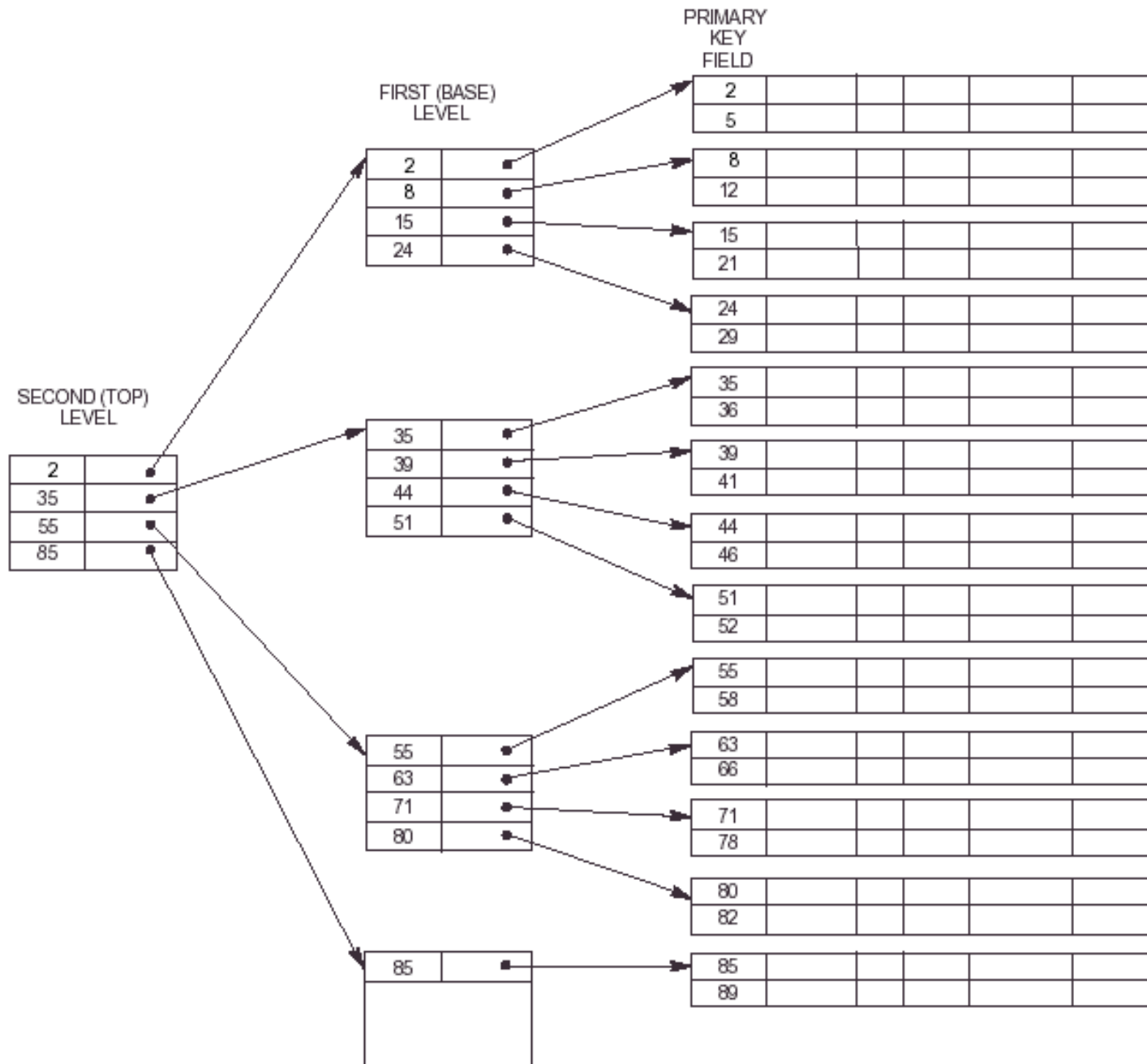
Multilevel Indexes

◆ Idea

- If the first level needs more than one block of disk storage → require a second level index
- If the second level needs more than one block of disk storage → require a third level index
- ...
- Repeat the preceding process until all the entries of some index level t fit in a single block

TWO-LEVEL INDEX

DATAFILE



Multilevel indexes (Cont.)

- ◆ bfr_i is called **fan-out** of the multilevel index.
Referred as **fo**.
- ◆ In any level, $bfr_i = fo$ (# of record per block)
 - Reason: all index entries are the same size
- ◆ r_1 : total number of records in level 1
- ◆ the 1st level needs (r_1/fo) block
= # of entries needed at the 2nd index level
= $r_2 = (r_1/fo)$

Multilevel indexes (Cont.)

- ◆ the 2nd level needs $(r2/fo)$ block
= # of entries needed at the 3rd index level
= $r3 = (r2/fo)$
- ◆ **Approximately** t level index, such that $r1/((fo)^t) \geq 1$
- ◆ A multilevel index with $r1$ first-level entries will have approximately t level, where $t = \log_{fo} (r1)$

B-Tree

- ◆ All leaf nodes are at the same level
- ◆ Figure
- ◆ Internal node of a B-tree
 $\langle P_1, \langle K_1, Pr_1 \rangle, P_2, \langle K_2, Pr_2 \rangle, \dots, \langle K_{q-1}, Pr_{q-1} \rangle, P_q \rangle$
 P_i - tree pointer
 Pr_i - data pointer (a pointer to the record whose search key field value = K_i , or to the data file block containing that record)

B-Tree (Cont.)

- ◆ Within each node, $K_1 < K_2 < \dots < K_{q-1}$
- ◆ For all search key field values X in the subtree pointed at by P_i
 - $K_{i-1} < X < K_i$, where $1 < i < q$
 - $X < K_i$, where $i=1$
 - $K_{i-1} < X$, where $i=q$;
- ◆ Leaf nodes have the same structure as internal nodes except that all of their tree pointers are null

B+ Tree

- ◆ Data pointers are stored only at the leaf nodes of the tree
- ◆ The leaf nodes have an entry for every value of the search field, along with a data pointer to the record (or block) if the search field is a key field
- ◆ The structure of leaf nodes differs from the structure of internal nodes
- ◆ Internal nodes of a B+ tree (figure)

Leaf node of a B⁺ tree

◆ $\langle \langle K_1, Pr_1 \rangle, \langle K_2, Pr_2 \rangle, \dots \langle K_{q-1}, Pr_{q-1} \rangle, P_{next} \rangle$

Pr_i is a data pointer

P_{next} points to the next leaf node of the B⁺ tree

◆ $K_1 < K_2 < \dots < K_{q-1}$

◆ Figure



These slides are based on the textbook:

R. Elmaseri and S. Navathe, *Fundamentals of Database Systems*, 7th Edition, Addison-Wesley.